

AcceIDSP Synthesis Tool

Release Notes

UG635 (v11.4) December 2, 2009





Xilinx is disclosing this Document and Intellectual Property (hereinafter “the Design”) to you for use in the development of designs to operate on, or interface with Xilinx FPGAs. Except as stated herein, none of the Design may be copied, reproduced, distributed, republished, downloaded, displayed, posted, or transmitted in any form or by any means including, but not limited to, electronic, mechanical, photocopying, recording, or otherwise, without the prior written consent of Xilinx. Any unauthorized use of the Design may violate copyright laws, trademark laws, the laws of privacy and publicity, and communications regulations and statutes.

Xilinx does not assume any liability arising out of the application or use of the Design; nor does Xilinx convey any license under its patents, copyrights, or any rights of others. You are responsible for obtaining any rights you may require for your use or implementation of the Design. Xilinx reserves the right to make changes, at any time, to the Design as deemed desirable in the sole discretion of Xilinx. Xilinx assumes no obligation to correct any errors contained herein or to advise you of any correction if such be made. Xilinx will not assume any liability for the accuracy or correctness of any engineering or technical support or assistance provided to you in connection with the Design.

THE DESIGN IS PROVIDED “AS IS” WITH ALL FAULTS, AND THE ENTIRE RISK AS TO ITS FUNCTION AND IMPLEMENTATION IS WITH YOU. YOU ACKNOWLEDGE AND AGREE THAT YOU HAVE NOT RELIED ON ANY ORAL OR WRITTEN INFORMATION OR ADVICE, WHETHER GIVEN BY XILINX, OR ITS AGENTS OR EMPLOYEES. XILINX MAKES NO OTHER WARRANTIES, WHETHER EXPRESS, IMPLIED, OR STATUTORY, REGARDING THE DESIGN, INCLUDING ANY WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, TITLE, AND NONINFRINGEMENT OF THIRD-PARTY RIGHTS.

IN NO EVENT WILL XILINX BE LIABLE FOR ANY CONSEQUENTIAL, INDIRECT, EXEMPLARY, SPECIAL, OR INCIDENTAL DAMAGES, INCLUDING ANY LOST DATA AND LOST PROFITS, ARISING FROM OR RELATING TO YOUR USE OF THE DESIGN, EVEN IF YOU HAVE BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES. THE TOTAL CUMULATIVE LIABILITY OF XILINX IN CONNECTION WITH YOUR USE OF THE DESIGN, WHETHER IN CONTRACT OR TORT OR OTHERWISE, WILL IN NO EVENT EXCEED THE AMOUNT OF FEES PAID BY YOU TO XILINX HEREUNDER FOR USE OF THE DESIGN. YOU ACKNOWLEDGE THAT THE FEES, IF ANY, REFLECT THE ALLOCATION OF RISK SET FORTH IN THIS AGREEMENT AND THAT XILINX WOULD NOT MAKE AVAILABLE THE DESIGN TO YOU WITHOUT THESE LIMITATIONS OF LIABILITY.

The Design is not designed or intended for use in the development of on-line control equipment in hazardous environments requiring fail-safe controls, such as in the operation of nuclear facilities, aircraft navigation or communications systems, air traffic control, life support, or weapons systems (“High-Risk Applications”). Xilinx specifically disclaims any express or implied warranties of fitness for such High-Risk Applications. You represent that use of the Design in such High-Risk Applications is fully at your risk.

© 2002-2009 Xilinx, Inc. All rights reserved. XILINX, the Xilinx logo, and other designated brands included herein are trademarks of Xilinx, Inc. All other trademarks are the property of their respective owners.

Table of Contents

Chapter 1: Release 11.4

Product Change Notice	5
System Requirements and Recommendations	5
Hardware Recommendations	5
Operating System and Software Requirements.....	5
Known Issues	5

Chapter 1: Release 11.3

Product Change Notice	7
System Requirements and Recommendations	7
Hardware Recommendations	7
Operating System and Software Requirements.....	7
Known Issues	7

Chapter 2: Release 11.2

Product Change Notice	9
System Requirements and Recommendations	9
Hardware Recommendations	9
Operating System and Software Requirements.....	9
Known Issues	9

Chapter 3: Release 11.1

AccelDSP Enhancements	11
New LogiCORE Support for Increased Performance.....	11
Global/Project Options	12
Directives	14
Generate Fixed Point Report Enhancements Aid in Achieving Higher Performance	15
AccelWare Tab and References Have Been Removed	18
System Requirements and Recommendations	18
Hardware Recommendations	18
Operating System and Software Requirements.....	19
Known Issues	19

Release 11.4

Product Change Notice

Starting with Release 11.2, further development of the AccelDSP synthesis tool has been discontinued. You may continue to use this version of the tool with ISE Design Suite 11. The tool will not be included in ISE Design Suite 12.

System Requirements and Recommendations

Hardware Recommendations

Recommendation	Notes
2.00 GB of RAM	
600 MB of hard disk space	Minimum Requirement
Xilinx® Hardware Co-Simulation Platform	Required for the Hardware Co-Simulation Flow

Operating System and Software Requirements

Requirement	Notes
Windows XP Professional 32-bit Operating System SP2	The AccelDSP synthesis tool does not support Windows Terminal Services.
Xilinx® ISE Design Suite Release 11.4	
MathWorks MATLAB® Version 2008b or 2009a	
MathWorks Simulink with Fixed-Point Toolbox Version 2008b or 2009a	Required for the System Generator Flow

Known Issues

Known issues with the AccelDSP synthesis tool can be found at the following Xilinx web site address:

<http://www.xilinx.com/support/answers/29595.htm>

Release 11.3

Product Change Notice

Starting with Release 11.2, further development of the AccelDSP synthesis tool has been discontinued. You may continue to use this version of the tool with ISE Design Suite 11. The tool will not be included in ISE Design Suite 12.

System Requirements and Recommendations

Hardware Recommendations

Recommendation	Notes
2.00 GB of RAM	
600 MB of hard disk space	Minimum Requirement
Xilinx® Hardware Co-Simulation Platform	Required for the Hardware Co-Simulation Flow

Operating System and Software Requirements

Requirement	Notes
Windows XP 32 bit Operating System SP2	The AccelDSP synthesis tool does not support Windows Terminal Services.
Xilinx® ISE Design Suite Release 11.2	
MathWorks MATLAB® Version 2008b or 2009a	
MathWorks Simulink with Fixed-Point Toolbox Version 2008b or 2009a	Required for the System Generator Flow

Known Issues

Known issues with the AccelDSP synthesis tool can be found at the following Xilinx web site address:

<http://www.xilinx.com/support/answers/29595.htm>

Release 11.2

Product Change Notice

Starting with this release, further development of the AccelDSP synthesis tool has been discontinued. You may continue to use this version of the tool with ISE Design Suite 11. The tool will not be included in ISE Design Suite 12.

System Requirements and Recommendations

Hardware Recommendations

Recommendation	Notes
2.00 GB of RAM	
600 MB of hard disk space	Minimum Requirement
Xilinx® Hardware Co-Simulation Platform	Required for the Hardware Co-Simulation Flow

Operating System and Software Requirements

Requirement	Notes
Windows XP 32 bit Operating System SP2	The AccelDSP synthesis tool does not support Windows Terminal Services.
Xilinx® ISE Design Suite Release 11.2	
MathWorks MATLAB® Version 2008b or 2009a	
MathWorks Simulink with Fixed-Point Toolbox Version 2008b or 2009a	Required for the System Generator Flow

Known Issues

Known issues with the AccelDSP synthesis tool can be found at the following Xilinx web site address:

<http://www.xilinx.com/support/answers/29595.htm>

Release 11.1

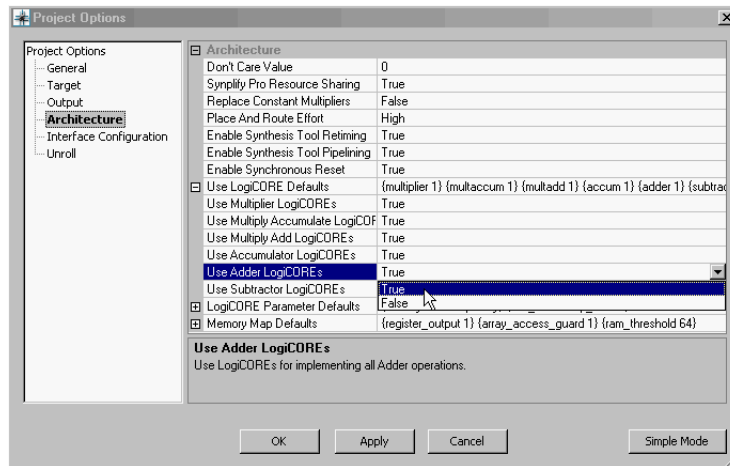
AccelDSP Enhancements

New LogiCORE Support for Increased Performance

Adder/Subtractor

With this release, the AccelDSP synthesis tool will now infer the Adder/Subtractor LogiCORE for VHDL flows.

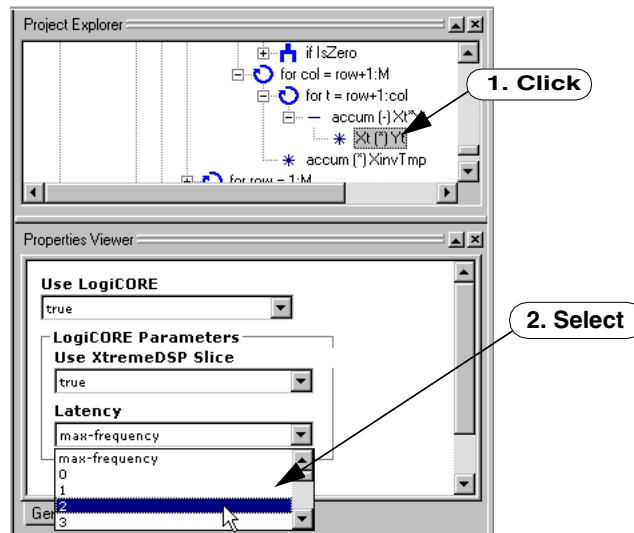
As shown below, this auto inference is not turned on by default, so you must change the **Use LogiCOREs Default** project option to turn this feature on.



New GUI Support for LogiCORE Parameters

For VHDL flows, inferred LogiCORE parameters can now be changed from the AccelDSP GUI. As shown below, simply select the associated operator from the Project Explorer

window or the Fixed Point Report, then change a parameter (like Latency) in the Properties Viewer window.



Global/Project Options

The following features have been added to AccelDSP and may be specified as Project Options or Global Options.

“Use LogiCORE Defaults” Global/Project Option Now On by Default

The **Use LogiCORE Defaults** project option is now turned on by default for VHDL flows. This causes AccelDSP to automatically infer a LogiCORE for each supported operator except the Adder and Subtractor. The default settings are as follows:

```
SetProjectOption -use_logicores {accum 1} {adder 0} {multaccum 1}
{multadd 1} {multiplier 1} {subtractor 0}
```

```
SetGlobalOption -use_logicores {accum 1} {adder 0} {multaccum 1}
{multadd 1} {multiplier 1} {subtractor 0}
```

You can turn on the use of the adder and the subtractor by setting the associated value to 1 (true).

This global/project option specifies the use of a LogiCORE for a particular type of operator like multiplier. You can turn off the use of a LogiCORE for any individual multiplier with a **Use LogiCORE** directive. For example:

```
SetDirective {for n.design.for m.a1 (*) in1} -use_logicore 0
```

New “LogiCORE Parameter Defaults” Global/Project Option

A new project option called **LogiCORE Parameter Defaults** has been created. This allows you to set LogiCORE parameters for latency and the mapping to the XtremeDSP Slice (which is the DSP48 element in the target technology). The default settings are as follows:

```
SetProjectOption -logicore_defaults {latency max-frequency}
{use_xtremedsp_slice 1}
```

```
SetGlobalOption -logicore_defaults {latency max-frequency}
{use_xtremedsp_slice 1}
```

Enhanced Register Inputs/Outputs Option for Higher Performance

In prior releases, the inputs to your design could be registered with one register and the outputs were registered with one implicit register by default. Now this feature has been enhanced to allow additional registers on the inputs and outputs.

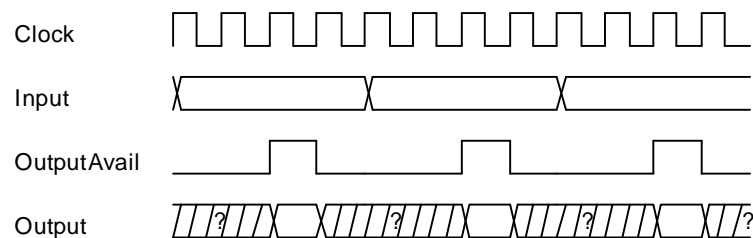
For example, assume that the critical path includes a long route from other hardware to the input of your design. By adding another register to the input, the register can be used by the place & route software to break the critical path. The project option setting might look like the following:

```
SetProjectOption -register_inputs 2
```

Now assume that you want to hold the output of your design longer to give the downstream hardware more time to capture the data. The command to add another register to the output might look like the following:

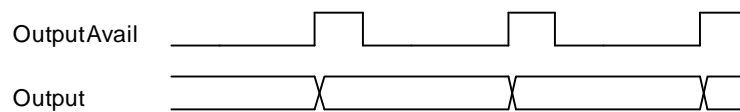
```
SetProjectOption -register_outputs 2
```

The figure below illustrates the timing diagram of a typical push-mode design with one implicit output register (the default). Notice that the output is valid only when the **OutputAvail** signal goes true for one clock cycle.



SetProjectOption -register_outputs 1

The figure below illustrates the interface timing when the project option **Register Outputs** is set to 2:



SetProjectOption -register_outputs 2

Notice that the output is valid now when the **OutputAvail** signal goes true and remains valid until the **OutputAvail** signal goes true again. This may be for more than one clock cycle. Although this adds additional cycles of latency, it gives the down stream hardware more time to capture the output data.

Note: Double registering the output is only valid for constant throughput designs with a push mode interface.

New Project Option “RAM Threshold”

A new Global/Project Option called **RAM Threshold** has been added to allow the automatic mapping of array variables to random access memory. The default is 64, so every array variable in your design that is equal to or greater than 64 elements will be automatically mapped to RAM. The benefit of mapping to RAM is reduced area and improved Fmax. You can turn off the automatic mapping to RAM by specifying a RAM Threshold of 0 (zero).

Directives

Memory Map Options “sp_sync_ram” and “sp_sync_rom” are Deprecated

Starting with this release, the memory map options **sp_sync_ram** and **sp_sync_rom** have been deprecated. If you have a current design that specifies one of these options, the option will be automatically replaced with **dp_sync_ram**.

New Memory Map Option “Array Access Guard”

AccelDSP has a new feature that allows you to request more aggressive scheduling for arrays in feedback loops. This feature is called **Array Access Guard** and is turned on (True) by default. When the Array Access Guard is on, AccelDSP does not pipeline feedback loops as aggressively.

If your design has array variables that are accessed in a known manner, but are not statically deterministic via the MATLAB code alone, and you want to improve the throughput of the design, you can turn off the Array Access Guard on one or more array variables, then re-run the AccelDSP flow to see if the throughput improves.

If you receive an error message (E-VERIFY-0007) during the Verify RTL step, then the act of removing one or more Array Access Guards is causing a conflict.

The variable(s) with conflicts are identified in the Verify RTL step of the AccelDSP log file (accel.log). To resolve the conflict, you must re-apply the Array Access Guard to the offending variable(s).

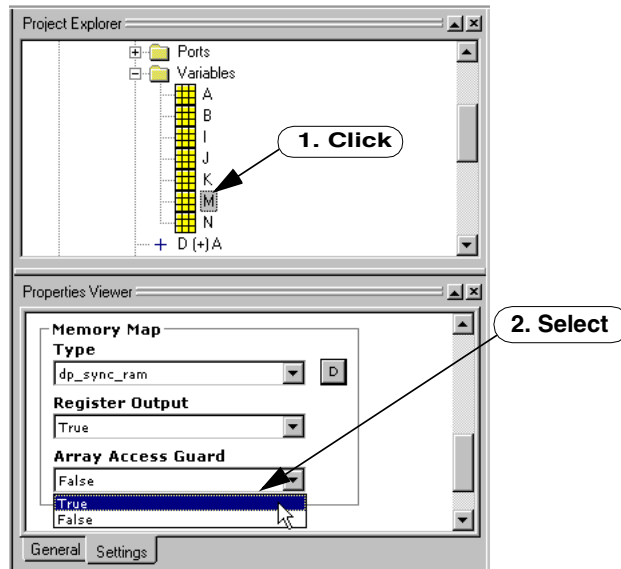
As an example, assume that you have several array variables in your design and you disable the Array Access Guard on each one to allow AccelDSP to more aggressively pipeline the design. You then re-run the AccelDSP flow and see the following message after the Verify RTL step:

```
#( E-VERIFY-0007): Simulating VHDL design: Modelsim Failed. This is due
to a pipeline register in a feedback loop.
# Remedy: Enable the Array Access Guard for feedback variable(s)
indicated in the accel_verify.log file and rerun Generate -fixedpoint.
```

Following the directions in the message, you scroll up in the Transcript window and see the following message from the ISE Simulator:

```
# ** Warning: Encountered array conflict - Please enable the Array
Access Guard for variable 'M'.
```

To remedy the conflict, you then select the variable M in the Project Explorer window, as shown below, and set the Array Access Guard in the Properties Viewer window back to **True**.



Generate Fixed Point Report Enhancements Aid in Achieving Higher Performance

Variables List Report

The figure below shows the new Variables List tab within the Generate Fixed-Point Report.

The screenshot shows the 'Generate Fixed Point Report' window. The 'Variables List' tab is selected and circled in blue. A callout bubble points to the 'dp_sync_ram' value in the 'Memory Map' column of the table, with the text 'Only one variable mapped to RAM'. The table contains the following data:

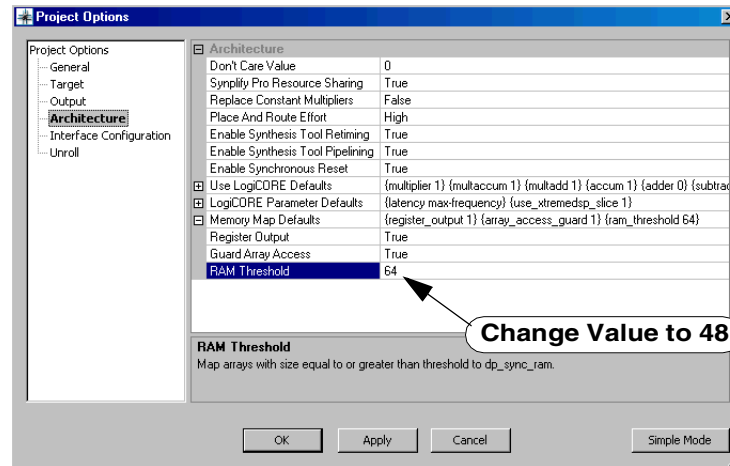
Variable	Shape	Elements ↑	Quantizer	Quantizer Source	Bits	Memory Map	Memory Map Source	Registered Output	Type
tap_delay	2 x 48	96	fixed floor wrap [16 0]	Auto Inferred	1536	dp_sync_ram	Automatically Inferred	Yes - Project Option	Double Persiste
DelayLine	3 x 20	60	fixed floor wrap [16 15]	MATLAB Source	960	nomap	Project Option	Yes - Project Option	Double Persiste
DelayLine	3 x 20	60	fixed floor wrap [16 15]	MATLAB Source	960	nomap	Project Option	Yes - Project Option	Double Persiste
CT	1 x 53	53	ufixed floor saturate [52 51]	Hierarchical Directive	2756	nomap	Project Option	Yes - Project Option	Double Consta
coeff	48 x 1	48	fixed floor wrap [16 15]	MATLAB Source	768	nomap	Project Option	Yes - Project Option	Double Persiste Consta

Figure 3-1: Variables List Fixed Point Report

This report lists each design variable and provides important information about the variable attributes. You can change an attribute by clicking on the variable row, where you

can change the attribute value in the Properties Viewer. In this example, you can see that only one array variable is mapped to Dual-Port RAM.

You can use this report to tune your design for maximum performance. In this case, only one variable is mapped to RAM because the default value for the new RAM Threshold project option is set to 64 (elements). Rather than apply a memmap directive to the other four variables listed below `tap_delay`, you can simply change the RAM Threshold project option to 48 as shown in the figure below.



The following figure shows how four additional array variables are mapped to memory with one change in the RAM Threshold project option.

FixedPointReport.htm

Generate Fixed Point Report

Elapsed Time: 15.41 seconds

Variables by Hierarchy | **Variables List** | Operators List | Loops List | Functions List

Variable	Shape	Elements ↑	Quantizer	Quantizer Source	Bits	Memory Map	Memory Map Source	Registered Output	Type
tap_delay	2 x 48	96	fixed floor wrap [16 0]	Auto Inferred	1536	dp_sync_ram	Automatically Inferred	Yes - Project Option	Double Persiste
DelayLine	3 x 20	60	fixed floor wrap [16 15]	MATLAB Source	960	dp_sync_ram	Automatically Inferred	Yes - Project Option	Double Persiste
DelayLine	3 x 20	60	fixed floor wrap [16 15]	MATLAB Source	960	dp_sync_ram	Automatically Inferred	Yes - Project Option	Double Persiste
CT	1 x 53	53	ufixed floor saturate [52 51]	Hierarchical Directive	2756	dp_sync_ram	Automatically Inferred	Yes - Project Option	Double Consta
coeff	48 x 1	48	fixed floor wrap [16 15]	MATLAB Source	768	dp_sync_ram	Automatically Inferred	Yes - Project Option	Double Persiste Consta

Four more variables mapped to RAM

Operators List Report

The figure below shows the new Operators List within the Generate Fixed-Point Report.

Operation	Input A # Bits	Input B # Bits	Add/Sub/Accum # Bits	Output # Bits ↑	LogiCORE	LogiCORE Source	Latency	Latency Source
Xt (*) Yt	12	24	N/A	36	Yes	Project Option	3	LogiCORE Defaults Project Option
v1_del (*) c	12	10	N/A	22	Yes	Project Option	3	LogiCORE Defaults Project Option
v2_del (*) s	12	10	N/A	22	Yes	Project Option	3	LogiCORE Defaults Project Option
v2_del (*) c	12	10	N/A	22	Yes	Project Option	3	LogiCORE Defaults Project

This report lists the name of each operator and provides important information about the operator parameters. You can change a parameter by clicking on the operator row, where you can change the parameter value in the Properties Viewer.

You can use this report to tune your design for maximum performance. For example, you can make sure that each operator is mapped to a LogiCORE, if possible, then change the LogiCORE latency to the desired value and adjust the quantization of each input. If you click on the column header of a particular parameter, the sort order for that column will reverse.

Loops List Report

The figure below shows the new Loops List within the Generate Fixed-Point Report.


Name	Start:Stride:End	Unrolled Iterations ↑	Unroll Value	Unroll Source
for Lg = 0:Lmax	0:1:9	10	Fully Rolled	Auto Inferred
for col_n = 0:N+1	0:1:4	5	Fully Rolled	Auto Inferred
for col = 1:N	1:1:3	3	Fully Rolled	Auto Inferred
for row = M-1:1	3:-1:1	3	Fully Rolled	Auto Inferred
for nn = 0:4:8	0:4:8	3	Fully Unrolled	Directive
for row = 1:M	1:1:3	3	Fully Rolled	Auto Inferred

This report shows the start, stride and end values for each loop, the total number of unrolled iterations, the unroll values and the source of the unroll value. You can change the

unroll value of a particular loop by first clicking on the loop row, where you can change the unroll value in the Properties Viewer.

Functions List Report

The figure below shows the new Functions List within the Generate Fixed-Point Report.



The screenshot shows a web browser window titled "FixedPointReport.htm" displaying the "Generate Fixed Point Report" interface. The report title is "Generate Fixed Point Report" with an elapsed time of 15.52 seconds. There are four tabs: "Variables by Hierarchy", "Variables List", "Operators List", and "Loops List", with "Functions List" being the active tab and circled in blue. Below the tabs is a table with three columns: "Name", "Implementation", and "Implementation Source".

Name ↓	Implementation	Implementation Source
accel_cmplxnorm	CORDIC	Directive
accel_qr_factor	Conventional Givens Rotations	Directive
accel_qr_inverse	Conventional Givens Rotations	Auto Inferred
accel_triangular_inverse	upper-triangular	Directive
log2	CORDIC	Directive
mtimes: I-K (*) P_cap_est	default	Auto Inferred

This report provides the name of each inferred function, the implementation and the source of the implementation (Auto Inferred or Directive). You can change the implementation by clicking on the function row, where you can change the implementation value in the Properties Viewer.

AccelWare Tab and References Have Been Removed

The **Create AccelWare** tab in the Open Project dialog box and all references to the term "Accelware" have been removed from the product. All MATLAB functions that were previously supported with AccelWare are still fully supported by AccelDSP. Refer to the topic [MATLAB for Synthesis Style Guide](#) for detailed information on available functions.

System Requirements and Recommendations

Hardware Recommendations

Recommendation	Notes
2.00 GB of RAM	
600 MB of hard disk space	Minimum Requirement
Xilinx® Hardware Co-Simulation Platform	Required for the Hardware Co-Simulation Flow

Operating System and Software Requirements

Requirement	Notes
Windows XP 32 bit Operating System SP2	The AccelDSP synthesis tool does not support Windows Terminal Services.
Xilinx® ISE Design Suite Release 11.1	
MathWorks MATLAB® Version 2008a or 2008b	
MathWorks Simulink with Fixed-Point Toolbox Version 2008a or 2008b	Required for the System Generator Flow

Known Issues

Known issues with the AccelDSP synthesis tool can be found at the following Xilinx web site address:

<http://www.xilinx.com/support/answers/29595.htm>

